Skyrme Crystals

Martin Speight Joint work with Derek Harland and Paul Leask SIG XI, Krakow, 19/6/23

University of Leeds

• When is a soliton on a torus

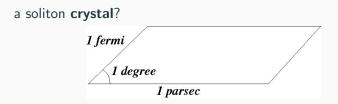
$$\varphi: \mathbb{R}^k / \Lambda \to N$$

a soliton crystal?

General question

• When is a soliton on a torus

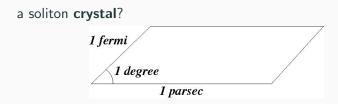
$$\varphi: \mathbb{R}^k / \Lambda \to N$$



General question

• When is a soliton on a torus

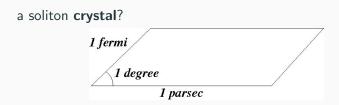
$$\varphi: \mathbb{R}^k / \Lambda \to N$$



• Clearly an artifact of b.c.s!

• When is a soliton on a torus

$$\varphi: \mathbb{R}^k / \Lambda \to N$$



- Clearly an artifact of b.c.s!
- φ should minimize energy E w.r.t. all variations of field and period lattice Λ

• All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.

- All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.
- Identify them all with $\mathbb{T}^k = \mathbb{R}^k / \mathbb{Z}^k$, the cubic torus.

- All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.
- Identify them all with $\mathbb{T}^k = \mathbb{R}^k / \mathbb{Z}^k$, the cubic torus.

$$\Lambda = \{n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + \dots + n_k \mathbf{X}_k : \mathbf{n} \in \mathbb{Z}^k\}$$
$$f : \mathbb{T}^3 \to \mathbb{R}^k / \Lambda, \qquad f(\mathbf{x}) = x_1 \mathbf{X}_1 + x_2 \mathbf{X}_2 + \dots + x_k \mathbf{X}_k$$
Now mfd is fixed, but **metric** depends on Λ

$$g_{\Lambda} = f^* g_{Euc} = g_{ij} dx_i dx_j, \qquad g_{ij} = \mathbf{X}_i \cdot \mathbf{X}_j \text{ const}$$

- All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.
- Identify them all with $\mathbb{T}^k = \mathbb{R}^k / \mathbb{Z}^k$, the cubic torus.

$$\Lambda = \{n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + \dots + n_k \mathbf{X}_k : \mathbf{n} \in \mathbb{Z}^k\}$$

$$f: \mathbb{T}^3 \to \mathbb{R}^k / \Lambda, \qquad f(\mathbf{x}) = x_1 \mathbf{X}_1 + x_2 \mathbf{X}_2 + \cdots + x_k \mathbf{X}_k$$

Now mfd is fixed, but **metric** depends on Λ

$$g_{\Lambda} = f^* g_{Euc} = g_{ij} dx_i dx_j, \qquad g_{ij} = \mathbf{X}_i \cdot \mathbf{X}_j \text{ const}$$

• Minimizing over $\Lambda \leftrightarrow$ minimizing over $g \in SPD_k$

- All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.
- Identify them all with $\mathbb{T}^k = \mathbb{R}^k / \mathbb{Z}^k$, the cubic torus.

$$\Lambda = \{n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + \dots + n_k \mathbf{X}_k : \mathbf{n} \in \mathbb{Z}^k\}$$

$$f: \mathbb{T}^3 \to \mathbb{R}^k / \Lambda, \qquad f(\mathbf{x}) = x_1 \mathbf{X}_1 + x_2 \mathbf{X}_2 + \cdots + x_k \mathbf{X}_k$$

Now mfd is fixed, but **metric** depends on Λ

$$g_{\Lambda} = f^* g_{Euc} = g_{ij} dx_i dx_j, \qquad g_{ij} = \mathbf{X}_i \cdot \mathbf{X}_j \text{ const}$$

- Minimizing over $\Lambda \leftrightarrow$ minimizing over $g \in SPD_k$
- $\bullet \ \ Criticality \leftrightarrow stress \ tensor$

- All tori are diffeomorphic through linear maps $\mathbb{R}^k \to \mathbb{R}^k$.
- Identify them all with $\mathbb{T}^k = \mathbb{R}^k / \mathbb{Z}^k$, the cubic torus.

$$\Lambda = \{n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + \dots + n_k \mathbf{X}_k : \mathbf{n} \in \mathbb{Z}^k\}$$

$$f: \mathbb{T}^3 \to \mathbb{R}^k / \Lambda, \qquad f(\mathbf{x}) = x_1 \mathbf{X}_1 + x_2 \mathbf{X}_2 + \cdots + x_k \mathbf{X}_k$$

Now mfd is fixed, but **metric** depends on Λ

$$g_{\Lambda} = f^* g_{Euc} = g_{ij} dx_i dx_j, \qquad g_{ij} = \mathbf{X}_i \cdot \mathbf{X}_j \text{ const}$$

- Minimizing over $\Lambda \leftrightarrow$ minimizing over $g \in SPD_k$
- Criticality \leftrightarrow stress tensor
- Manoeuvre works provided $E(\varphi, g)$ is geometrically natural

$$E(\varphi \circ f,g) = E(\varphi,(f^{-1})^*g)$$

$E: \textit{Maps}(\mathbb{T}^3, \textit{SU}(2)) \times \textit{SPD}_3 \rightarrow \mathbb{R}$

Two minimization problems:

 Fix g. Does E(·, g) : Maps → ℝ attain a min in each homotopy class?

$E: \textit{Maps}(\mathbb{T}^3, \textit{SU}(2)) \times \textit{SPD}_3 \rightarrow \mathbb{R}$

Two minimization problems:

 Fix g. Does E(·, g) : Maps → ℝ attain a min in each homotopy class? YES! (at least in H¹ - low regularity) – Auckly, Kapitanski

$E: \textit{Maps}(\mathbb{T}^3, \textit{SU}(2)) \times \textit{SPD}_3 \rightarrow \mathbb{R}$

Two minimization problems:

- Fix g. Does E(·, g) : Maps → ℝ attain a min in each homotopy class? YES! (at least in H¹ - low regularity) – Auckly, Kapitanski
- Fix φ ? Does $E(\varphi, \cdot) : SPD_3 \to \mathbb{R}$ attain a min?

$E: Maps(\mathbb{T}^3, SU(2)) \times SPD_3 \to \mathbb{R}$

Two minimization problems:

- Fix g. Does E(·, g) : Maps → ℝ attain a min in each homotopy class? YES! (at least in H¹ - low regularity) – Auckly, Kapitanski
- Fix φ? Does E(φ, ·): SPD₃ → ℝ attain a min? YES! And it's a global min, and there are no other critical points!

The Skyrme energy

$$E(\varphi,g) = \int_{\mathbb{T}^3} \left(-\frac{1}{2} \operatorname{tr}(L_i L_j) g^{ij} - \frac{1}{16} \operatorname{tr}([L_i, L_j][L_k, L_l]) g^{ik} g^{jl} + V(\varphi) \right) \sqrt{|g|} d^3x$$

• Fix $\varphi : \mathbb{T}^3 \to SU(2), E_{\varphi} : SPD_3 \to \mathbb{R}$

The Skyrme energy

$$E(\varphi,g) = \int_{\mathbb{T}^3} \left(-\frac{1}{2} \operatorname{tr}(L_i L_j) g^{ij} - \frac{1}{16} \operatorname{tr}([L_i, L_j][L_k, L_l]) g^{ik} g^{jl} + V(\varphi) \right) \sqrt{|g|} d^3x$$

• Fix
$$\varphi : \mathbb{T}^3 \to SU(2), E_{\varphi} : SPD_3 \to \mathbb{R}$$

$$E_{arphi}(g) = \sqrt{|g|}\operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}}\operatorname{tr}(\Omega g) + C_0\sqrt{|g|}$$

- Constants:
 - H, Ω : symmetric positive **semidefinite** matrices
 - *C* ≥ 0
- Nondegeneracy assumption: φ is C¹ and immersive somewhere (automatic if B ≠ 0).

The Skyrme energy

$$E(\varphi,g) = \int_{\mathbb{T}^3} \left(-\frac{1}{2} \operatorname{tr}(L_i L_j) g^{ij} - \frac{1}{16} \operatorname{tr}([L_i, L_j][L_k, L_l]) g^{ik} g^{jl} + V(\varphi) \right) \sqrt{|g|} d^3x$$

• Fix
$$\varphi : \mathbb{T}^3 \to SU(2), E_{\varphi} : SPD_3 \to \mathbb{R}$$

$$E_{\varphi}(g) = \sqrt{|g|}\operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}}\operatorname{tr}(\Omega g) + C_0\sqrt{|g|}$$

- Constants:
 - H, Ω : symmetric positive **semidefinite** matrices
 - *C* ≥ 0
- Nondegeneracy assumption: φ is C¹ and immersive somewhere (automatic if B ≠ 0).
 ⇒ H, Ω ∈ SPD₃

$$E_4 = rac{1}{4}\int_{\mathbb{T}^3} |arphi^*\omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G)\otimes \mathfrak{g}$$

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \to (\Lambda^2 T^*M), \qquad X \mapsto \iota_X \operatorname{vol}_0$

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $\operatorname{vol}_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism $TM \otimes \mathfrak{g} \to (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \operatorname{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \otimes \mathfrak{g} \to (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

• This vector field is independent of g!

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \otimes \mathfrak{g} \to (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

- This vector field is independent of g!
- Similarly, define X_{φ}^{g} s.t. $\iota_{X_{\varphi}^{g}} \operatorname{vol}_{g} = \varphi^{*} \omega$

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \otimes \mathfrak{g} \to (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

- This vector field is independent of g!
- Similarly, define X_{φ}^{g} s.t. $\iota_{X_{\omega}^{g}} \operatorname{vol}_{g} = \varphi^{*} \omega$
- Clearly $\sqrt{|g|}X_{\varphi}^{g} = X_{\varphi}$

$$E_4 = rac{1}{4} \int_{\mathbb{T}^3} |arphi^* \omega|_g^2 \mathrm{vol}_g, \qquad \omega \in \Omega^2(G) \otimes \mathfrak{g}$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \otimes \mathfrak{g} \to (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

- This vector field is independent of g!
- Similarly, define X_{φ}^{g} s.t. $\iota_{X_{\varphi}^{g}} \operatorname{vol}_{g} = \varphi^{*} \omega$
- Clearly $\sqrt{|g|}X_{\varphi}^{g} = X_{\varphi}$

• Now
$$X_{\varphi}^{g} = \sharp_{g} *_{g} \varphi^{*} \omega$$
, so

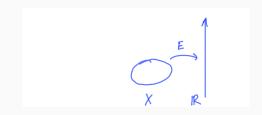
$$|\varphi^*\omega|_g^2 = |X_{\varphi}^g|_g^2 = \frac{1}{|g|}g(X_{\varphi}, X_{\varphi})$$

• Hence

$$egin{aligned} E_4(g) &= rac{g_{ij}}{\sqrt{|g|}} \Omega_{ij} \ \Omega_{ij} &= rac{1}{4} \int_{\mathcal{T}^3} h(X_i,X_j) d^3x \end{aligned}$$

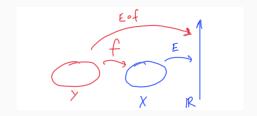
Existence of minimizing metrics

$$E_{arphi} = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$



Existence of minimizing metrics

$$E_{\varphi} = \operatorname{tr}(H\Sigma^{-1}) + \operatorname{tr}(\Omega\Sigma) + rac{C}{\det\Sigma}, \qquad \Sigma = rac{g}{\sqrt{|g|}}$$



Existence of minimizing metrics

$$E_{\varphi} = \operatorname{tr}(H\Sigma^{-1}) + \operatorname{tr}(\Omega\Sigma) + \frac{C}{\det\Sigma}, \qquad \Sigma = \frac{g}{\sqrt{|g|}}$$

- $f: (0,\infty)^3 \times O(3) \to SPD_3, \ f(\lambda,\mathscr{O}) = \mathscr{O}D_\lambda \mathscr{O}^T$
- We will show $E \circ f : (0,\infty)^3 \times O(3) \to \mathbb{R}$ attains a min

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega\mathscr{O}D_{\lambda}) + \frac{\mathcal{C}}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega\mathscr{O}D_{\lambda}) + \frac{\mathcal{C}}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

• Consider the smooth functions ${\it O}(3)
ightarrow (0,\infty)$

$$\mathscr{O} \mapsto (\mathscr{O}^{-1} \mathcal{H} \mathscr{O})_{\mathsf{aa}}, \qquad \mathscr{O} \mapsto (\mathscr{O}^{-1} \Omega \mathscr{O})_{\mathsf{aa}}$$

Since O(3) is compact, they're all bounded away from 0

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega\mathscr{O}D_{\lambda}) + \frac{\mathcal{C}}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

• Consider the smooth functions $O(3)
ightarrow (0,\infty)$

$$\mathscr{O}\mapsto (\mathscr{O}^{-1}\mathcal{H}\mathscr{O})_{\mathsf{aa}}, \qquad \mathscr{O}\mapsto (\mathscr{O}^{-1}\Omega\mathscr{O})_{\mathsf{aa}}$$

Since O(3) is compact, they're all bounded away from 0

• Exists $\alpha > 0$ s.t. for all (λ, \mathscr{O}) ,

$$(E \circ f)(\lambda, \mathscr{O}) \ge \alpha \left(\frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3} + \lambda_1 + \lambda_2 + \lambda_3\right).$$
 (*)

• Consider now a sequence $(\lambda_n, \mathscr{O}_n)$ s.t.

$$(E \circ f)(\boldsymbol{\lambda}_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

• Consider now a sequence $(\lambda_n, \mathscr{O}_n)$ s.t.

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

By (*) exists K > 1 s.t. λ_n ∈ [K⁻¹, K]³, so sequence has a convergent subsequence (λ_n, 𝒪_n) → (λ_{*}, 𝒪_{*}).

• Consider now a sequence $(\lambda_n, \mathscr{O}_n)$ s.t.

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

- By (*) exists K > 1 s.t. λ_n ∈ [K⁻¹, K]³, so sequence has a convergent subsequence (λ_n, 𝒪_n) → (λ_{*}, 𝒪_{*}).
- Continuity of E implies (E ∘ f)(λ_{*}, 𝒞_{*}) = E_{*}, i.e. E ∘ f attains a min

• Claim *E* has no other critical points.

- Claim *E* has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!

- Claim E has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!
- $f: M \to \mathbb{R}$ is strictly convex if, for all geodesics γ in M, $(f \circ \gamma)'' > 0$

- Claim *E* has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!
- $f: M \to \mathbb{R}$ is strictly convex if, for all geodesics γ in M, $(f \circ \gamma)'' > 0$
- Metric on SPD₃?



$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$



$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$

• Complete, negatively curved, unique geodesic between any pair of points.

$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\Sigma \mapsto A\Sigma A^T$.

$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\Sigma \mapsto A\Sigma A^T$.
- $\iota: \Sigma \mapsto \Sigma^{-1}$ is an isometry.

$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\Sigma \mapsto A\Sigma A^T$.
- $\iota: \Sigma \mapsto \Sigma^{-1}$ is an isometry.
- Geodesic through \mathbb{I}_3 : $\Sigma(t) = \exp(t\xi)$

$$\|\dot{\boldsymbol{\Sigma}}\|^2 = tr(\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}\dot{\boldsymbol{\Sigma}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\Sigma \mapsto A\Sigma A^T$.
- $\iota: \Sigma \mapsto \Sigma^{-1}$ is an isometry.
- Geodesic through \mathbb{I}_3 : $\Sigma(t) = \exp(t\xi)$
- Geodesic through $\Sigma(0)$: $\Sigma(t) = A \exp(t\xi) A^T$ where $AA^T = \Sigma(0)$

$$\begin{split} E_4(\Sigma) &= \operatorname{tr}(\Omega\Sigma) \\ E_4(\Sigma(t)) &= \operatorname{tr}(\Omega A \exp(t\xi) A^T) \\ &= \operatorname{tr}(\Omega_A \exp(t\xi)), \qquad \Omega_A = A^T \Omega A \\ \frac{d^2}{dt^2} E_4(\Sigma(t)) \bigg|_{t=0} &= \operatorname{tr}(\Omega_A \xi^2) > 0 \end{split}$$

• So *E*₄ is strictly convex.

$E_2(\Sigma) = \operatorname{tr}(H\Sigma^{-1}) = (\widehat{E}_4 \circ \iota)(\Sigma)$

$$E_2(\Sigma) = \operatorname{tr}(H\Sigma^{-1}) = (\widehat{E}_4 \circ \iota)(\Sigma)$$

• ι is an isometry, so E_2 is strictly convex

$$E_2(\Sigma) = \operatorname{tr}(H\Sigma^{-1}) = (\widehat{E}_4 \circ \iota)(\Sigma)$$

- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \to \mathbb{R}$ is convex

$$E_2(\Sigma) = \operatorname{tr}(H\Sigma^{-1}) = (\widehat{E}_4 \circ \iota)(\Sigma)$$

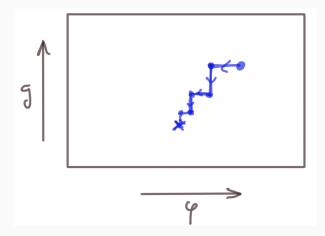
- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \to \mathbb{R}$ is convex
- Hence $E_0 = \det \circ \iota$ is convex

$$E_2(\Sigma) = \operatorname{tr}(H\Sigma^{-1}) = (\widehat{E}_4 \circ \iota)(\Sigma)$$

- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \to \mathbb{R}$ is convex
- Hence $E_0 = \det \circ \iota$ is convex
- So E = E₂ + E₄ + E₀ is strictly convex. Hence it has at most one critical point. (Assume Σ_{*}, Σ_{**} both cps, apply Rolle's Theorem to (E ∘ γ)' where γ is the geodesic between them.)

The numerical problem

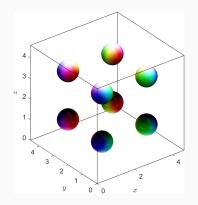
$$\ddot{x} = -\operatorname{grad} E(x)$$



J.M. Speight (University of Leeds)

The Kugler-Shtrikman crystal (massless model)

 $E = E_2 + E_4$



 $(x_1, x_2, x_3) \mapsto (x_2, x_3, x_1)$ $(\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (\varphi_0, \varphi_2, \varphi_3, \varphi_1)$

 $(x_1, x_2, x_3) \mapsto (x_2, -x_1, x_3)$ $(\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (\varphi_0, \varphi_2, -\varphi_1, \varphi_3)$

 $\begin{aligned} & (x_1, x_2, x_3) \mapsto (x_1 + 1/2, x_2, x_3) \\ & (\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (-\varphi_0, -\varphi_1, \varphi_2, \varphi_3) \end{aligned}$

The Kugler-Shtrikman crystal: turning on the pion mass

• Massless model has global *SO*(4) symmetry: no boundary to break this

The Kugler-Shtrikman crystal: turning on the pion mass

- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions

- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions
- Turn on pion mass:

$$E_t = E_0 + t \int_{\mathbb{T}^3} (1 - \varphi_0) \sqrt{|g|} d^3 x$$

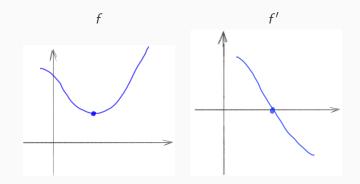
What happens to these critical points?

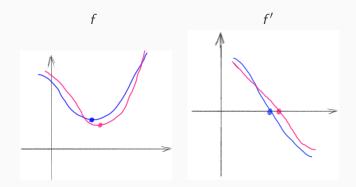
- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions
- Turn on pion mass:

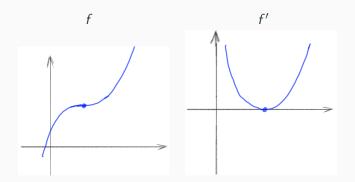
$$E_t = E_0 + t \int_{\mathbb{T}^3} (1 - \varphi_0) \sqrt{|g|} d^3 x$$

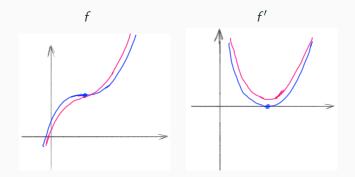
What happens to these critical points?

• No reason to expect **degenerate** critical points to survive perturbation









• Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.

• Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.

 $E_t(gx) = E_t(x)$

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.

$$\Gamma = \{g : gx_0 = x_0\}$$

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x_0 as c.p. of restriction $E_0|: X^{\Gamma} \to \mathbb{R}$.

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x_0 as c.p. of **restriction** $E_0|: X^{\Gamma} \to \mathbb{R}$.

$$X^{\mathsf{\Gamma}} = \{x : \forall g \in \mathsf{\Gamma}, gx = x\}$$

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x₀ as c.p. of restriction E₀|: X^Γ → ℝ. Maybe it's nondegenerate as a c.p. of E₀|

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x₀ as c.p. of restriction E₀|: X^Γ → ℝ. Maybe it's nondegenerate as a c.p. of E₀|
- Then it continues as c.p. of $E_t|: X^{\Gamma} \to \mathbb{R}$ by IFT applied to $dE_t|$

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x₀ as c.p. of restriction E₀|: X^Γ → ℝ. Maybe it's nondegenerate as a c.p. of E₀|
- Then it continues as c.p. of $E_t|: X^{\Gamma} \to \mathbb{R}$ by IFT applied to $dE_t|$
- Continues as c.p. of $E_t: X \to \mathbb{R}$ by PSC

- Say $E_t: X \to \mathbb{R}$ has nontrivial symmetry group G.
- Say (degenerate) c.p. x_0 of E_0 has stabilizer $\Gamma < G$.
- Think of x₀ as c.p. of restriction E₀|: X^Γ → ℝ. Maybe it's nondegenerate as a c.p. of E₀|
- Then it continues as c.p. of $E_t|: X^{\Gamma} \to \mathbb{R}$ by IFT applied to $dE_t|$
- Continues as c.p. of $E_t : X \to \mathbb{R}$ by PSC
- Nondegenerate \Rightarrow isolated.

Symmetry analysis

• Apply this to

$$E_t = E_2 + E_4 + t \int_{\mathbb{T}^3} (1 - arphi_0) \mathsf{vol}_g$$

- $X = C^2(\mathbb{T}^3, SU(2)) \times SPD_3$
- $G = SO(3) \times Aut(T^3)$

Symmetry analysis

• Apply this to

$$E_t = E_2 + E_4 + t \int_{\mathbb{T}^3} (1 - \varphi_0) \operatorname{vol}_g$$

- $X = C^2(\mathbb{T}^3, SU(2)) \times SPD_3$
- $G = SO(3) \times Aut(T^3)$
- Identify points p in SO(4) orbit of (φ_{KS}, g_{KS}) with isotropy group Γ < G s.t.

 $X^{\Gamma} \cap \operatorname{orbit} = \{p\}$

Symmetry analysis

• Apply this to

$$E_t = E_2 + E_4 + t \int_{\mathbb{T}^3} (1 - \varphi_0) \operatorname{vol}_g$$

• $X = C^2(\mathbb{T}^3, SU(2)) \times SPD_3$

•
$$G = SO(3) \times Aut(T^3)$$

 Identify points p in SO(4) orbit of (φ_{KS}, g_{KS}) with isotropy group Γ < G s.t.

 $X^{\Gamma} \cap \operatorname{orbit} = \{p\}$

Then p is an **isolated** c.p. of $E|X^{\Gamma}$

Symmetry analysis

• Apply this to

$$E_t = E_2 + E_4 + t \int_{\mathbb{T}^3} (1 - \varphi_0) \operatorname{vol}_g$$

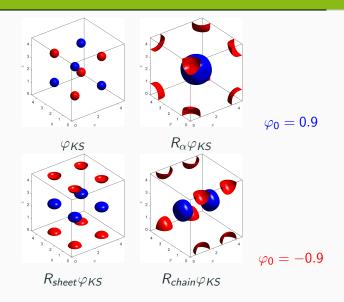
- $X = C^2(\mathbb{T}^3, SU(2)) \times SPD_3$
- $G = SO(3) \times Aut(T^3)$
- Identify points p in SO(4) orbit of (φ_{KS}, g_{KS}) with isotropy group Γ < G s.t.

 $X^{\Gamma} \cap \operatorname{orbit} = \{p\}$

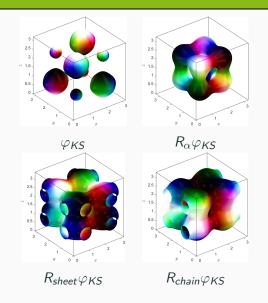
Then p is an **isolated** c.p. of $E|X^{\Gamma}$

• Reduces to a problem in representation theory of subgroups of ${\cal O}_h$

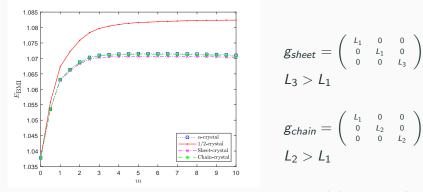
The KS crystals that (should) survive



Skyrme crystals at pion mass t = 1



Energy ordering: sheet < chain $< \alpha <$ KS



trigonal, but not cubic!

$$\begin{aligned} U_{KS} &= \begin{pmatrix} 165.2 & 0 & 0 \\ 0 & 165.2 & 0 \\ 0 & 0 & 165.2 \end{pmatrix}, \quad U_{\alpha} = \begin{pmatrix} 135.5 & 0 & 0 \\ 0 & 135.5 & 0 \\ 0 & 0 & 167.3 \end{pmatrix}, \\ U_{sheet} &= \begin{pmatrix} 135.8 & 0 & 0 \\ 0 & 135.8 & 0 \\ 0 & 0 & 166.8 \end{pmatrix}, \quad U_{chain} = \begin{pmatrix} 135.6 & 0 & 0 \\ 0 & 135.7 & 0 \\ 0 & 0 & 167.2 \end{pmatrix} \end{aligned}$$

J.M. Speight (University of Leeds)

.

• Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$

- Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$

- Baryon density $ho = B/\sqrt{\det g} = B\det\Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$
- Existence of global min follows immediately

$$E \ge \alpha(\lambda_1 + \lambda_2 + \lambda_3 + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3})$$

confines minimizing sequence to a compact subset of $\det^{-1}(\rho/B)$

- Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$
- Existence of global min follows immediately

$$E \ge \alpha(\lambda_1 + \lambda_2 + \lambda_3 + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3})$$

confines minimizing sequence to a compact subset of $\det^{-1}(\rho/B)$

• General geodesic $\Sigma(t) = Ae^{t\xi}A^T$

$$\det \Sigma(t) = \det A^2 e^{t \operatorname{tr} \xi} = \det \Sigma(0) e^{t \operatorname{tr} \xi}$$

- Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$
- Existence of global min follows immediately

$$E \ge \alpha(\lambda_1 + \lambda_2 + \lambda_3 + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3})$$

confines minimizing sequence to a compact subset of $\det^{-1}(\rho/B)$

• General geodesic $\Sigma(t) = Ae^{t\xi}A^T$

$$\det \Sigma(t) = \det A^2 e^{t \operatorname{tr} \xi} = \det \Sigma(0) e^{t \operatorname{tr} \xi}$$

• Tangent to det⁻¹(det $\Sigma(0)$) iff tr $\xi = 0$

- Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$
- Existence of global min follows immediately

$$E \ge lpha(\lambda_1 + \lambda_2 + \lambda_3 + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3})$$

confines minimizing sequence to a compact subset of $\det^{-1}(\rho/B)$

• General geodesic $\Sigma(t) = Ae^{t\xi}A^T$

$$\det \Sigma(t) = \det A^2 e^{t \operatorname{tr} \xi} = \det \Sigma(0) e^{t \operatorname{tr} \xi}$$

- Tangent to det⁻¹(det $\Sigma(0)$) iff tr $\xi = 0$
- But then it stays on det⁻¹(det $\Sigma(0)$) for all t!

- Baryon density $\rho = B/\sqrt{\det g} = B \det \Sigma$
- Minimize $E(\Sigma)$ over a level set of det : $SPD_3 \rightarrow (0,\infty)$
- Existence of global min follows immediately

$$E \ge lpha(\lambda_1 + \lambda_2 + \lambda_3 + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3})$$

confines minimizing sequence to a compact subset of $\det^{-1}(\rho/B)$

• General geodesic $\Sigma(t) = Ae^{t\xi}A^T$

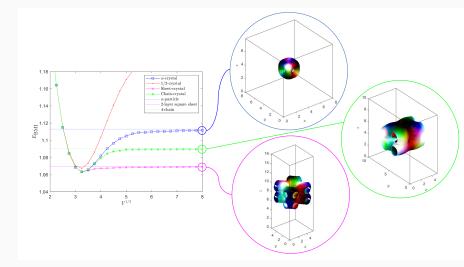
$$\det \Sigma(t) = \det A^2 e^{t \operatorname{tr} \xi} = \det \Sigma(0) e^{t \operatorname{tr} \xi}$$

- Tangent to det⁻¹(det $\Sigma(0)$) iff tr $\xi = 0$
- But then it stays on det⁻¹(det $\Sigma(0)$) for all t!

• Level sets of det are totally geodesic!

- Level sets of det are totally geodesic!
- $E : \det^{-1}(\rho/B) \to \mathbb{R}$ is strictly convex!

- Level sets of det are totally geodesic!
- $E : \det^{-1}(\rho/B) \to \mathbb{R}$ is strictly convex!
- Global min is the only c.p.



• Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!

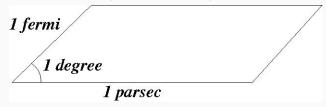
- Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!
- Many examples in condensed matter (cf work with Tom Winyard et al). True also for nuclear Skyrme model with massive pions

- Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!
- Many examples in condensed matter (cf work with Tom Winyard et al). True also for nuclear Skyrme model with massive pions
- Extreme case: baby Skyrme model $\varphi:M^2 \to S^2$

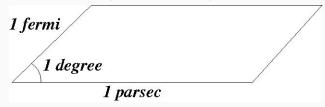
$$E(\varphi) = \int_M (rac{1}{2} |d\varphi|^2 + rac{1}{2} |arphi^* \omega|^2 + V(arphi)).$$

Given **any** period lattice $\Lambda \subset \mathbb{R}^2$, can cook up a smooth potential $V : S^2 \to [0, \infty)$ s.t. $E(\varphi, g)$ has a global min at (φ_*, g_Λ) with φ_* degree 2 and holomorphic.

• So this crazy lattice **is** the period lattice of a baby Skyrmion crystal, at least for a (highly contrived) choice of V!



• So this crazy lattice **is** the period lattice of a baby Skyrmion crystal, at least for a (highly contrived) choice of V!



• Existence result at fixed volume very generic

 $E(\varphi,g) = E_2(\varphi,g) + \text{positive, geom nat}$

any dimension. Compactness argument works. E.g. $\omega\text{-meson}$ Skyrme model