Skyrme Crystals

Martin Speight Joint work with Derek Harland and Paul Leask 14/3/23

University of Leeds



$$\varphi: (M,g) \to (G,h)$$

$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

• $\varphi(\infty) = e$, disjoint homotopy classes labelled by $B \in \mathbb{Z}$

$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

- $\varphi(\infty) = e$, disjoint homotopy classes labelled by $B \in \mathbb{Z}$
- Left-invariant Maurer-Cartan form $\mu \in \Omega^1(\mathcal{G}) \otimes \mathfrak{g}$

$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

- $\varphi(\infty)=e$, disjoint homotopy classes labelled by $B\in\mathbb{Z}$
- Left-invariant Maurer-Cartan form $\mu \in \Omega^1(G) \otimes \mathfrak{g}$
- Associated two-form $\omega \in \Omega^2(G) \otimes \mathfrak{g}$, $\omega(X,Y) = [\mu(X),\mu(Y)]$

$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

- $\varphi(\infty) = e$, disjoint homotopy classes labelled by $B \in \mathbb{Z}$
- Left-invariant Maurer-Cartan form $\mu \in \Omega^1(G) \otimes \mathfrak{g}$
- Associated two-form $\omega \in \Omega^2(G) \otimes \mathfrak{g}$, $\omega(X, Y) = [\mu(X), \mu(Y)]$
- Skyrme energy

$$E(arphi) = \int_{M} |darphi|^2 + rac{1}{4} |arphi^* \omega|^2 + V(arphi)$$

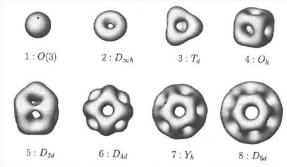
$$\varphi: (M,g) \to (G,h)$$
 e.g. $\mathbb{R}^3 \to SU(2)$

- $\varphi(\infty) = e$, disjoint homotopy classes labelled by $B \in \mathbb{Z}$
- Left-invariant Maurer-Cartan form $\mu \in \Omega^1(G) \otimes \mathfrak{g}$
- Associated two-form $\omega \in \Omega^2(G) \otimes \mathfrak{g}$, $\omega(X, Y) = [\mu(X), \mu(Y)]$
- Skyrme energy

$$E(arphi) = \int_{M} |darphi|^2 + rac{1}{4} |arphi^* \omega|^2 + V(arphi)$$

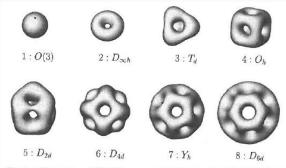
- Faddeev bound: $E(\varphi) \ge E_0|B|$, unattainable
- Degree B minimizer \leftrightarrow nucleus of atomic weight B

• Numerics



Battye and Sutcliffe

• Numerics



Battye and Sutcliffe

E/*BE*₀ monotonically decreases e.g. 1.232 (*B* = 1), 1.096 (*B* = 8).

• Suggests Skyrmions may be able to form a **crystal** $\varphi : \mathbb{R}^3 / \Lambda \to G, \qquad \Lambda = \{ n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + n_3 \mathbf{X}_3 \ : \ \mathbf{n} \in \mathbb{Z}^3 \}$

- Suggests Skyrmions may be able to form a **crystal** $\varphi : \mathbb{R}^3 / \Lambda \to G, \qquad \Lambda = \{ n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + n_3 \mathbf{X}_3 \ : \ \mathbf{n} \in \mathbb{Z}^3 \}$
- V = 0: Castillejo et al, Kugler et al, chose Λ = LZ³, found B = 4 minimizer for each L > 0, minimized over L. Found φ with E/BE₀ = 1.036.

- Suggests Skyrmions may be able to form a **crystal** $\varphi : \mathbb{R}^3 / \Lambda \to G, \qquad \Lambda = \{ n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + n_3 \mathbf{X}_3 : \mathbf{n} \in \mathbb{Z}^3 \}$
- V = 0: Castillejo et al, Kugler et al, chose Λ = LZ³, found B = 4 minimizer for each L > 0, minimized over L. Found φ with E/BE₀ = 1.036.
- But is this really a crystal? Given any Λ, B, there exists a degree B minimizer φ : ℝ³/Λ → G (Auckly, Kapitanski).



- Suggests Skyrmions may be able to form a **crystal** $\varphi : \mathbb{R}^3 / \Lambda \to G, \qquad \Lambda = \{ n_1 \mathbf{X}_1 + n_2 \mathbf{X}_2 + n_3 \mathbf{X}_3 : \mathbf{n} \in \mathbb{Z}^3 \}$
- V = 0: Castillejo et al, Kugler et al, chose Λ = LZ³, found B = 4 minimizer for each L > 0, minimized over L. Found φ with E/BE₀ = 1.036.
- But is this really a crystal? Given any Λ, B, there exists a degree B minimizer φ : ℝ³/Λ → G (Auckly, Kapitanski).



For most Λ , lifted map $\mathbb{R}^3 \to G$ clearly isn't a genuine solution: artifact of bc's.

Given a minimizer φ : ℝ^k/Λ → N of some energy functional E(φ), when is the lifted map ℝ^k → N a genuine crystal?

- Given a minimizer φ : ℝ^k/Λ → N of some energy functional E(φ), when is the lifted map ℝ^k → N a genuine crystal?
- Should be critical (in fact stable) with respect to variations of Λ too.

• All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3$.

- All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3.$
- Identify them all with M = ℝ³/ℤ³, the cubic torus. Now mfd is fixed, but metric depends on Λ

$$g_{\Lambda} = g_{ij} dx_i dx_j, \qquad g_{ij} = \mathbf{X}_i \cdot \mathbf{X}_j \text{ const}$$

- All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3.$
- Identify them all with M = ℝ³/ℤ³, the cubic torus. Now mfd is fixed, but metric depends on Λ g_Λ = g_{ii} dx_i dx_i, g_{ii} = X_i · X_i const
- So now

$$E(arphi, g) = \int_{\mathcal{T}^3} (|darphi|_g^2 + rac{1}{4}|arphi^*\omega|_g^2 + V(arphi)) \mathrm{vol}_g$$

and we want to minimize w.r.t. both $\varphi \in C_B^2(T^3, G)$ and $g \in SPD_3$ (space of symmetric positive definite 3×3 matrices)

- All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3.$
- Identify them all with M = ℝ³/ℤ³, the cubic torus. Now mfd is fixed, but metric depends on Λ g_Λ = g_{ii} dx_i dx_i, g_{ii} = X_i · X_i const
- So now

$$E(arphi, g) = \int_{\mathcal{T}^3} (|darphi|_g^2 + rac{1}{4}|arphi^*\omega|_g^2 + V(arphi)) \mathrm{vol}_g$$

and we want to minimize w.r.t. both $\varphi \in C_B^2(T^3, G)$ and $g \in SPD_3$ (space of symmetric positive definite 3×3 matrices)

• Does a min exist? Dunno, but...

- All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3.$
- Identify them all with M = ℝ³/ℤ³, the cubic torus. Now mfd is fixed, but metric depends on Λ
 g_Λ = g_{ii} dx_i dx_i, g_{ii} = X_i · X_i const
- So now

$$E(\varphi,g) = \int_{\mathcal{T}^3} (|d\varphi|_g^2 + \frac{1}{4}|\varphi^*\omega|_g^2 + V(\varphi)) \operatorname{vol}_g$$

and we want to minimize w.r.t. both $\varphi \in C_B^2(T^3, G)$ and $g \in SPD_3$ (space of symmetric positive definite 3×3 matrices)

- Does a min exist? Dunno, but...
- Fix g: E(φ) certainly attains a min in each homotopy class (at least in H¹ - low regularity) – Auckly, Kapitanski

- All tori are diffeomorphic through linear maps $\mathbb{R}^3 \to \mathbb{R}^3.$
- Identify them all with M = ℝ³/ℤ³, the cubic torus. Now mfd is fixed, but metric depends on Λ
 g_Λ = g_{ii} dx_i dx_i, g_{ii} = X_i · X_i const
- So now

$$E(arphi, g) = \int_{\mathcal{T}^3} (|darphi|_g^2 + rac{1}{4}|arphi^*\omega|_g^2 + V(arphi)) \mathrm{vol}_g$$

and we want to minimize w.r.t. both $\varphi \in C_B^2(T^3, G)$ and $g \in SPD_3$ (space of symmetric positive definite 3×3 matrices)

- Does a min exist? Dunno, but...
- Fix g: E(φ) certainly attains a min in each homotopy class (at least in H¹ - low regularity) – Auckly, Kapitanski
- What if we fix φ ? Does E(g) attain a min?

Want to think of E, for a fixed φ : T³ = ℝ³/ℤ³ → G as a function of the metric g on T³:

$$E_{\varphi}:SPD_3 \rightarrow \mathbb{R}$$

Want to think of E, for a fixed φ : T³ = ℝ³/ℤ³ → G as a function of the metric g on T³:

$$E_{\varphi}: SPD_3 \rightarrow \mathbb{R}$$

 Theorem Let φ : T³ → G be C¹ and somewhere immersive. Then E_φ attains a global minimum at some g_{*} ∈ SPD₃ and has no other critical points.

Want to think of E, for a fixed φ : T³ = ℝ³/ℤ³ → G as a function of the metric g on T³:

$$E_{\varphi}: SPD_3 \rightarrow \mathbb{R}$$

- Theorem Let φ : T³ → G be C¹ and somewhere immersive. Then E_φ attains a global minimum at some g_{*} ∈ SPD₃ and has no other critical points.
- Proof: First note that

$$E_{\varphi}(g) = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + \frac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$

where $H, \Omega \in SPD_3$ and $C \in [0, \infty)$ are fixed.

$$\begin{split} E_2(g) &= \int_{T^3} \varphi^* h(\partial_i, \partial_j) g^{ij} \sqrt{|g|} d^3 x = \sqrt{|g|} g_{ij}^{-1} H_{ij} \\ H_{ij} &:= \int_{T^3} \varphi^* h(\partial_i, \partial_j) d^3 x \\ E_0(g) &= \int_{T^3} V(\varphi) \sqrt{|g|} d^3 x = C \sqrt{|g|} \\ C &:= \int_{T^3} V(\varphi) d^3 x \end{split}$$

$$E_{2}(g) = \int_{T^{3}} \varphi^{*} h(\partial_{i}, \partial_{j}) g^{ij} \sqrt{|g|} d^{3}x = \sqrt{|g|} g_{ij}^{-1} H_{ij}$$
$$H_{ij} := \int_{T^{3}} \varphi^{*} h(\partial_{i}, \partial_{j}) d^{3}x$$
$$E_{0}(g) = \int_{T^{3}} V(\varphi) \sqrt{|g|} d^{3}x = C \sqrt{|g|}$$
$$C := \int_{T^{3}} V(\varphi) d^{3}x$$

• Let
$$vol_0 = dx_1 \wedge dx_2 \wedge dx_3$$
. Isomorphism

$$TM \to (\Lambda^2 T^*M), \qquad X \mapsto \iota_X \operatorname{vol}_0$$

• Let $vol_0 = dx_1 \wedge dx_2 \wedge dx_3$. Isomorphism

 $TM \otimes \mathfrak{g} \rightarrow (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

• Let
$$vol_0 = dx_1 \wedge dx_2 \wedge dx_3$$
. Isomorphism

$$TM \otimes \mathfrak{g}
ightarrow (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

• This vector field is independent of g!

• Let
$$vol_0 = dx_1 \wedge dx_2 \wedge dx_3$$
. Isomorphism

$$TM \otimes \mathfrak{g}
ightarrow (\Lambda^2 T^*M) \otimes \mathfrak{g}, \qquad X \mapsto \iota_X \mathrm{vol}_0$$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

• This vector field is independent of g!

$$X_{\varphi} = \sqrt{|g|} \, \sharp_g \, *_g \varphi^* \omega.$$

• Let
$$vol_0 = dx_1 \wedge dx_2 \wedge dx_3$$
. Isomorphism

$$TM\otimes \mathfrak{g}
ightarrow (\Lambda^2 T^*M)\otimes \mathfrak{g}, \qquad X\mapsto \iota_X \mathrm{vol}_0$$

Define X_{φ} s.t. $\iota_{X_{\varphi}} \operatorname{vol}_{0} = \varphi^{*} \omega$.

• This vector field is independent of g!

$$\begin{split} X_{\varphi} &= \sqrt{|g|} \, \sharp_g *_g \varphi^* \omega. \\ E_4(g) &= \frac{1}{4} \|\varphi^* \omega\|_{L^2(g)}^2 = \frac{1}{4} \int_{T^3} \frac{1}{|g|} g(X_{\varphi}, X_{\varphi}) \text{vol}_g = \frac{g_{ij}}{\sqrt{|g|}} \Omega_{ij} \\ \Omega_{ij} &= \frac{1}{4} \int_{T^3} h(X_i, X_j) d^3 x \end{split}$$

$$E_{\varphi}(g) = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$

 H, Ω clearly symmetric and positive semi-definite. Hypothesis on φ implies they're positive definite.

$$E_{\varphi}(g) = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$

 H, Ω clearly symmetric and positive semi-definite. Hypothesis on φ implies they're positive definite.

• Define
$$\mathscr{G} = g/\sqrt{|g|}$$
. Then

$$E: SPD_3 \to \mathbb{R}, \qquad E(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) + \operatorname{tr}(\Omega \mathscr{G}) + \frac{C}{\det \mathscr{G}}.$$

$$E_{\varphi}(g) = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$

 H, Ω clearly symmetric and positive semi-definite. Hypothesis on φ implies they're positive definite.

• Define
$$\mathscr{G} = g/\sqrt{|g|}$$
. Then

$$E: SPD_3 \to \mathbb{R}, \qquad E(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) + \operatorname{tr}(\Omega \mathscr{G}) + \frac{C}{\det \mathscr{G}}.$$

• Surjection $f: (0,\infty)^3 \times O(3) \rightarrow SPD_3$

$$(\boldsymbol{\lambda},\mathscr{O})\mapsto \mathscr{O}\left(egin{array}{ccc} \lambda_1 & 0 & 0 \ 0 & \lambda_2 & 0 \ 0 & 0 & \lambda_3 \end{array}
ight)\mathscr{O}^{\mathsf{T}}=\mathscr{O}D_{\boldsymbol{\lambda}}\mathscr{O}^{\mathsf{T}}$$

$$E_{\varphi}(g) = \sqrt{|g|} \operatorname{tr}(Hg^{-1}) + rac{1}{\sqrt{|g|}} \operatorname{tr}(\Omega g) + C\sqrt{|g|}$$

 H, Ω clearly symmetric and positive semi-definite. Hypothesis on φ implies they're positive definite.

• Define
$$\mathscr{G} = g/\sqrt{|g|}$$
. Then

$$E: SPD_3 \to \mathbb{R}, \qquad E(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) + \operatorname{tr}(\Omega \mathscr{G}) + \frac{C}{\det \mathscr{G}}.$$

• Surjection $f: (0,\infty)^3 \times O(3) \rightarrow SPD_3$

$$(\boldsymbol{\lambda},\mathscr{O})\mapsto \mathscr{O}\left(egin{array}{ccc} \lambda_1 & 0 & 0 \ 0 & \lambda_2 & 0 \ 0 & 0 & \lambda_3 \end{array}
ight)\mathscr{O}^{\mathsf{T}}=\mathscr{O}D_{\boldsymbol{\lambda}}\mathscr{O}^{\mathsf{T}}$$

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(H(\mathscr{O}D_{\lambda}\mathscr{O}^{-1})^{-1}) + \operatorname{tr}(\Omega \mathscr{O}D_{\lambda}\mathscr{O}^{-1}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$
$$= \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega \mathscr{O}D_{\lambda}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(H(\mathscr{O}D_{\lambda}\mathscr{O}^{-1})^{-1}) + \operatorname{tr}(\Omega \mathscr{O}D_{\lambda}\mathscr{O}^{-1}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$
$$= \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega \mathscr{O}D_{\lambda}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

• Consider the smooth functions $O(3)
ightarrow (0,\infty)$

$$\mathscr{O}\mapsto (\mathscr{O}^{-1}\mathcal{H}\mathscr{O})_{\mathsf{aa}}, \qquad \mathscr{O}\mapsto (\mathscr{O}^{-1}\Omega\mathscr{O})_{\mathsf{aa}}$$

Since O(3) is compact, they're all bounded away from 0

$$(E \circ f)(\lambda, \mathscr{O}) = \operatorname{tr}(H(\mathscr{O}D_{\lambda}\mathscr{O}^{-1})^{-1}) + \operatorname{tr}(\Omega \mathscr{O}D_{\lambda}\mathscr{O}^{-1}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$
$$= \operatorname{tr}(\mathscr{O}^{-1}H\mathscr{O}D_{\lambda}^{-1}) + \operatorname{tr}(\mathscr{O}^{-1}\Omega \mathscr{O}D_{\lambda}) + \frac{C}{\lambda_{1}\lambda_{2}\lambda_{3}}$$

• Consider the smooth functions ${\it O}(3)
ightarrow (0,\infty)$

$$\mathscr{O}\mapsto (\mathscr{O}^{-1}\mathcal{H}\mathscr{O})_{\mathsf{aa}}, \qquad \mathscr{O}\mapsto (\mathscr{O}^{-1}\Omega\mathscr{O})_{\mathsf{aa}}$$

Since O(3) is compact, they're all bounded away from 0

• Exists $\alpha > 0$ s.t. for all (λ, \mathscr{O}) ,

$$(E \circ f)(\lambda, \mathscr{O}) \ge \alpha \left(\frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \frac{1}{\lambda_3} + \lambda_1 + \lambda_2 + \lambda_3 \right).$$
 (*)

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

By (*) exists K > 1 s.t. λ_n ∈ [K⁻¹, K]³, so sequence has a convergent subsequence (λ_n, 𝒪_n) → (λ_{*}, 𝒪_{*}).

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

- By (*) exists K > 1 s.t. λ_n ∈ [K⁻¹, K]³, so sequence has a convergent subsequence (λ_n, 𝒪_n) → (λ_{*}, 𝒪_{*}).
- Continuity of E implies (E ∘ f)(λ_{*}, 𝒞_{*}) = E_{*}, i.e. E ∘ f attains a min

$$(E \circ f)(\lambda_n, \mathscr{O}_n) \to E_* = \inf E \circ f$$

- By (*) exists K > 1 s.t. λ_n ∈ [K⁻¹, K]³, so sequence has a convergent subsequence (λ_n, 𝒪_n) → (λ_{*}, 𝒪_{*}).
- Continuity of E implies (E ∘ f)(λ_{*}, 𝒞_{*}) = E_{*}, i.e. E ∘ f attains a min
- Let $\mathscr{G}_* = \mathscr{O}_* D_{\lambda_*} \mathscr{O}_*^{-1} \in SPD_3$. E_{φ} attains a min at $g_* = \mathscr{G}_* / \det(\mathscr{G}_*)$.

• Claim *E* has no other critical points.

- Claim *E* has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!

- Claim E has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!
- $f: M \to \mathbb{R}$ is strictly convex if, for all geodesics γ in M, $(f \circ \gamma)'' > 0$

- Claim *E* has no other critical points.
- $E: SPD_3 \to \mathbb{R}$ is strictly convex!
- $f: M \to \mathbb{R}$ is strictly convex if, for all geodesics γ in M, $(f \circ \gamma)'' > 0$
- Metric on SPD₃?



$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$



$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$

• Complete, negatively curved, unique geodesic between any pair of points.

$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\mathscr{G} \mapsto A\mathscr{G}A^T$.

$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\mathscr{G} \mapsto A\mathscr{G}A^T$.
- $\iota: \mathscr{G} \mapsto \mathscr{G}^{-1}$ is an isometry.

$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\mathscr{G} \mapsto A\mathscr{G}A^T$.
- $\iota: \mathscr{G} \mapsto \mathscr{G}^{-1}$ is an isometry.
- Geodesic through \mathbb{I}_3 : $\mathscr{G}(t) = \exp(t\xi)$

$$\|\dot{\mathscr{G}}\|^2 = \operatorname{tr}(\mathscr{G}^{-1}\dot{\mathscr{G}}\mathscr{G}^{-1}\dot{\mathscr{G}})$$

- Complete, negatively curved, unique geodesic between any pair of points.
- Invariant under $GL(3,\mathbb{R})$ action $\mathscr{G} \mapsto A\mathscr{G}A^T$.
- $\iota: \mathscr{G} \mapsto \mathscr{G}^{-1}$ is an isometry.
- Geodesic through \mathbb{I}_3 : $\mathscr{G}(t) = \exp(t\xi)$
- Geodesic through $\mathscr{G}(0)$: $\mathscr{G}(t) = A \exp(t\xi) A^T$ where $AA^T = \mathscr{G}(0)$

$$\begin{split} E_4(\mathscr{G}) &= \operatorname{tr}(\Omega \mathscr{G}) \\ E_4(\mathscr{G}(t)) &= \operatorname{tr}(\Omega A \exp(t\xi) A^T) \\ &= \operatorname{tr}(\Omega_A \exp(t\xi)), \qquad \Omega_A = A^T \Omega A \\ \frac{d^2}{dt^2} E_4(\mathscr{G}(t)) \bigg|_{t=0} &= \operatorname{tr}(\Omega_A \xi^2) > 0 \end{split}$$

• So *E*₄ is strictly convex.



$$E_2(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) = (\widehat{E}_4 \circ \iota)(\mathscr{G})$$

$$E_2(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) = (\widehat{E}_4 \circ \iota)(\mathscr{G})$$

• ι is an isometry, so E_2 is strictly convex

$$E_2(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) = (\widehat{E}_4 \circ \iota)(\mathscr{G})$$

- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \rightarrow \mathbb{R}$ is strictly convex

$$E_2(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) = (\widehat{E}_4 \circ \iota)(\mathscr{G})$$

- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \to \mathbb{R}$ is strictly convex
- Hence $E_0 = \det \circ \iota$ is strictly convex

$$E_2(\mathscr{G}) = \operatorname{tr}(H\mathscr{G}^{-1}) = (\widehat{E}_4 \circ \iota)(\mathscr{G})$$

- ι is an isometry, so E_2 is strictly convex
- det : $SPD_3 \to \mathbb{R}$ is strictly convex
- Hence $E_0 = \det \circ \iota$ is strictly convex
- So E = E₂ + E₄ + E₀ is strictly convex. Hence it has at most one critical point. (Assume G_{*}, G_{**} both cps, apply Rolle's Theorem to (E ∘ γ)' where γ is the geodesic between them.)

• Minimize $E: C^2(T^3, S^3) \times SPD_3 \rightarrow \mathbb{R}$

• Minimize
$$E: \underbrace{C^2(T^3, S^3) \times SPD_3}_{M} \to \mathbb{R}$$

• Minimize
$$E: \underbrace{C^2(T^3, S^3) \times SPD_3}_{M} \to \mathbb{R}$$

• Newton flow: pick $x(0) \in M$, solve

$$\ddot{x} = -(\operatorname{grad} E)(x)$$

with $\dot{x}(0) = 0$.

• Minimize
$$E: \underbrace{C^2(T^3, S^3) \times SPD_3}_M \to \mathbb{R}$$

• Arrested Newton flow: pick $x(0) \in M$, solve

$$\ddot{x} = -(\operatorname{grad} E)(x)$$

with $\dot{x}(0) = 0$.

• Set $\dot{x}(t) = 0$ if $\langle \dot{x}, \operatorname{grad} E \rangle > 0$

• Minimize
$$E: \underbrace{C^2(T^3, S^3) \times SPD_3}_M \to \mathbb{R}$$

• Arrested Newton flow: pick $x(0) \in M$, solve

$$\ddot{x} = -(\operatorname{grad} E)(x)$$

with $\dot{x}(0) = 0$.

- Set $\dot{x}(t) = 0$ if $\langle \dot{x}, \operatorname{grad} E \rangle > 0$
- Terminate when $\| \operatorname{grad} E \| < tol$

The numerical problem

• Minimize
$$E: \underbrace{C^2(T^3, S^3) \times SPD_3}_{M} \to \mathbb{R}$$

• Arrested Newton flow: pick $x(0) \in M$, solve

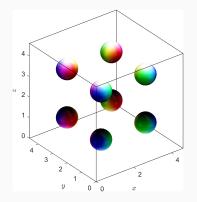
$$\ddot{x} = -(\operatorname{grad} E)(x)$$

with $\dot{x}(0) = 0$.

- Set $\dot{x}(t) = 0$ if $\langle \dot{x}, \operatorname{grad} E \rangle > 0$
- Terminate when $\| \operatorname{grad} E \| < tol$
- Converges much faster than gradient flow.

The Kugler-Shtrikman crystal (massless model)

$$E = \|d\varphi\|^2 + \frac{1}{4}\|\varphi^*\omega\|^2$$



 $(x_1, x_2, x_3) \mapsto (x_2, x_3, x_1)$ $(\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (\varphi_0, \varphi_2, \varphi_3, \varphi_1)$

 $(x_1, x_2, x_3) \mapsto (x_2, -x_1, x_3)$ $(\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (\varphi_0, \varphi_2, -\varphi_1, \varphi_3)$

 $\begin{aligned} & (x_1, x_2, x_3) \mapsto (x_1 + 1/2, x_2, x_3) \\ & (\varphi_0, \varphi_1, \varphi_2, \varphi_3) \mapsto (-\varphi_0, -\varphi_1, \varphi_2, \varphi_3) \end{aligned}$

The Kugler-Shtrikman crystal: turning on the pion mass

• Massless model has global *SO*(4) symmetry: no boundary to break this

The Kugler-Shtrikman crystal: turning on the pion mass

- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions

- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions
- Turn on pion mass:

$$E_t = E_0 + t \int_{T^3} (1 - \varphi_0) \sqrt{|g|} d^3 x$$

What happens to these critical points?

- Massless model has global *SO*(4) symmetry: no boundary to break this
- Above solution φ_{KS}, g_{KS} = LI₃ is one point on a SO(4) orbit of solutions
- Turn on pion mass:

$$E_t = E_0 + t \int_{T^3} (1 - \varphi_0) \sqrt{|g|} d^3 x$$

What happens to these critical points?

• No reason to expect **degenerate** critical points to survive perturbation

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

• E_0 has degenerate minima at (0, y) (symmetry orbit)

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- *E*₀ has degenerate minima at (0, *y*) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- *E*₀ has degenerate minima at (0, *y*) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E_0 disappear

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- E_0 has degenerate minima at (0, y) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E₀ disappear
- (0,0) survives. Why? Protected by symmetry

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- E_0 has degenerate minima at (0, y) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E₀ disappear
- (0,0) survives. Why? Protected by symmetry
- Restrict E_t to $(\mathbb{R}^2)^{\Gamma} = \mathbb{R} \times \{0\}$

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- E_0 has degenerate minima at (0, y) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E₀ disappear
- (0,0) survives. Why? Protected by symmetry
- Restrict E_t to $(\mathbb{R}^2)^{\Gamma} = \mathbb{R} \times \{0\}$
- E_0 has a nondegenerate critical point at (0, 0):

$$d \nabla E_0 | : T_{(0,0)}(\mathbb{R}^2)^{\Gamma} o T_{(0,0)}(\mathbb{R}^2)^{\Gamma}$$
 is invertible

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- E_0 has degenerate minima at (0, y) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E_0 disappear
- (0,0) survives. Why? Protected by symmetry
- Restrict E_t to $(\mathbb{R}^2)^{\Gamma} = \mathbb{R} \times \{0\}$
- E_0 has a nondegenerate critical point at (0, 0):

 $d \nabla E_0 | : T_{(0,0)}(\mathbb{R}^2)^{\Gamma} o T_{(0,0)}(\mathbb{R}^2)^{\Gamma}$ is invertible

• Solution of $\nabla E_t | = 0$ persists (for t suff small) by IFT

$$E_t: \mathbb{R}^2 \to \mathbb{R}, \qquad E_t(x, y) = x^2 + ty^2$$

- E_0 has degenerate minima at (0, y) (symmetry orbit)
- t > 0: translation symmetry broken to $\Gamma : (x, y) \mapsto (x, -y)$
- Almost all critical points of E_0 disappear
- (0,0) survives. Why? Protected by symmetry
- Restrict E_t to $(\mathbb{R}^2)^{\Gamma} = \mathbb{R} \times \{0\}$
- E_0 has a nondegenerate critical point at (0, 0):

 $d\nabla E_0|: T_{(0,0)}(\mathbb{R}^2)^{\Gamma} \to T_{(0,0)}(\mathbb{R}^2)^{\Gamma} \quad \text{is invertible}$

- Solution of $\nabla E_t | = 0$ persists (for t suff small) by IFT
- Also a solution of $\nabla E_t = 0$ by PSC

$$E_t: \underbrace{C^2(T^3, S^3) \times SPD_3}_{M} \to \mathbb{R}$$
• E_0 invariant under action of $G_0 = SO(4) \times Aut(T^3)$

$$E_t:\underbrace{C^2(T^3,S^3)\times SPD_3}_M\to\mathbb{R}$$

- E_0 invariant under action of $G_0 = SO(4) \times Aut(T^3)$
- $E_{t>0}$ invariant under action of $G_1 = SO(3) \times Aut(T^3)$

$$E_t:\underbrace{C^2(T^3,S^3)\times SPD_3}_M\to\mathbb{R}$$

- E_0 invariant under action of $G_0 = SO(4) \times Aut(T^3)$
- $E_{t>0}$ invariant under action of $G_1 = SO(3) \times Aut(T^3)$
- Stabilizer of φ_{KS} in G_0 : $\Gamma \cong O_h$

$$E_t:\underbrace{C^2(T^3,S^3)\times SPD_3}_M\to\mathbb{R}$$

- E_0 invariant under action of $G_0 = SO(4) \times Aut(T^3)$
- $E_{t>0}$ invariant under action of $G_1 = SO(3) \times Aut(T^3)$
- Stabilizer of φ_{KS} in G_0 : $\Gamma \cong O_h$
- Stabilizer of $(R, e) \cdot \varphi_{KS}$ in G_1 $(R \in SO(4))$:

 $\Gamma_R = (R, e) \Gamma(R, e)^{-1} \cap [SO(3) \times Aut(T^3)]$

For a.e. $R \in SO(4)$, $\Gamma_R = \{(e, e)\}$

$$E_t:\underbrace{C^2(T^3,S^3)\times SPD_3}_M\to\mathbb{R}$$

- E_0 invariant under action of $G_0 = SO(4) \times Aut(T^3)$
- $E_{t>0}$ invariant under action of $G_1 = SO(3) \times Aut(T^3)$
- Stabilizer of φ_{KS} in G_0 : $\Gamma \cong O_h$
- Stabilizer of $(R, e) \cdot \varphi_{KS}$ in G_1 $(R \in SO(4))$:

$$\Gamma_R = (R, e)\Gamma(R, e)^{-1} \cap [SO(3) \times Aut(T^3)]$$

For a.e. $R \in SO(4)$, $\Gamma_R = \{(e, e)\}$

Then M^{Γ_R} = M and (R, e) · φ_{KS} is certainly **not** a nondegenerate cp of E₀|

For

$$R \in \left\{ \mathbb{I}_{4}, \underbrace{\left(\begin{array}{c} (0,1,1,1)/\sqrt{3} \\ * \end{array}\right)}_{R_{\alpha}}, \underbrace{\left(\begin{array}{c} (0,0,0,1) \\ * \end{array}\right)}_{R_{sheet}}, \underbrace{\left(\begin{array}{c} (0,0,1,1)/\sqrt{2} \\ * \end{array}\right)}_{R_{chain}} \right\}$$

 Γ_R is nontrivial, and M^{Γ_R} intersects the SO(4) orbit of φ_{KS} transversely: implies $(R, e) \cdot \varphi_{KS}$ is an **isolated** cp of $E_0|: M^{\Gamma_R} \to \mathbb{R}$

• For

$$R \in \left\{ \mathbb{I}_{4}, \underbrace{\left(\begin{array}{c} (0,1,1,1)/\sqrt{3} \\ * \end{array}\right)}_{R_{\alpha}}, \underbrace{\left(\begin{array}{c} (0,0,0,1) \\ * \end{array}\right)}_{R_{sheet}}, \underbrace{\left(\begin{array}{c} (0,0,1,1)/\sqrt{2} \\ * \end{array}\right)}_{R_{chain}} \right\}$$

 Γ_R is nontrivial, and M^{Γ_R} intersects the SO(4) orbit of φ_{KS} transversely: implies $(R, e) \cdot \varphi_{KS}$ is an **isolated** cp of $E_0|: M^{\Gamma_R} \to \mathbb{R}$

 Assume further that (R, e) · φ_{KS} is a nondegenerate cp of E₀|. IFT implies cp persists to E_{t>0}|, t small

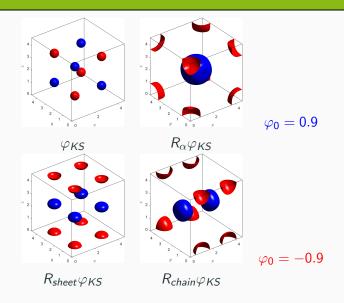
• For

$$R \in \left\{ \mathbb{I}_{4}, \underbrace{\left(\begin{array}{c} (0,1,1,1)/\sqrt{3} \\ * \end{array}\right)}_{R_{\alpha}}, \underbrace{\left(\begin{array}{c} (0,0,0,1) \\ * \end{array}\right)}_{R_{sheet}}, \underbrace{\left(\begin{array}{c} (0,0,1,1)/\sqrt{2} \\ * \end{array}\right)}_{R_{chain}} \right\}$$

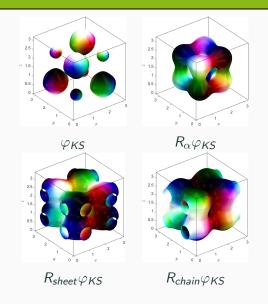
 Γ_R is nontrivial, and M^{Γ_R} intersects the SO(4) orbit of φ_{KS} transversely: implies $(R, e) \cdot \varphi_{KS}$ is an **isolated** cp of $E_0|: M^{\Gamma_R} \to \mathbb{R}$

- Assume further that (R, e) · φ_{KS} is a nondegenerate cp of E₀|. IFT implies cp persists to E_{t>0}|, t small
- PSC implies $\varphi(t)$ also a cp of E_t .

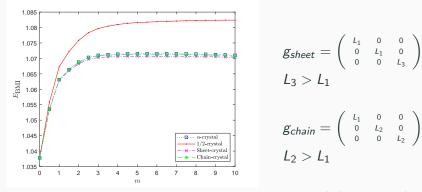
The KS crystals that (should) survive



Skyrme crystals at pion mass t = 1



Energy ordering: sheet < chain $< \alpha <$ KS



trigonal, but not cubic!

$$\begin{aligned} & U_{KS} = \begin{pmatrix} 165.2 & 0 & 0 \\ 0 & 165.2 & 0 \\ 0 & 0 & 165.2 \end{pmatrix}, \quad & U_{\alpha} = \begin{pmatrix} 135.5 & 0 & 0 \\ 0 & 135.5 & 0 \\ 0 & 0 & 167.3 \end{pmatrix}, \\ & U_{sheet} = \begin{pmatrix} 135.8 & 0 & 0 \\ 0 & 135.8 & 0 \\ 0 & 0 & 166.8 \end{pmatrix}, \quad & U_{chain} = \begin{pmatrix} 135.6 & 0 & 0 \\ 0 & 135.7 & 0 \\ 0 & 0 & 167.2 \end{pmatrix} \end{aligned}$$

J.M. Speight (University of Leeds)

.

• Baryon density
$$\rho = \frac{B}{\sqrt{\det g}}$$

- Baryon density $\rho = \frac{B}{\sqrt{\det g}}$
- Optimal lattice at fixed ρ ? Minimize

 $E: C^2_B(T^3, S^3) imes \det^{-1}(B^2/
ho^2) o \mathbb{R}$

I.e. restrict *E* to level set of det : $SPD_3 \rightarrow (0, \infty)$.

- Baryon density $\rho = \frac{B}{\sqrt{\det g}}$
- Optimal lattice at fixed ρ ? Minimize

 $E: C^2_B(T^3, S^3) imes \det^{-1}(B^2/
ho^2)
ightarrow \mathbb{R}$

I.e. restrict *E* to level set of det : $SPD_3 \rightarrow (0, \infty)$.

• Same argument implies (for fixed φ) existence of global minimizing g

- Baryon density $\rho = \frac{B}{\sqrt{\det g}}$
- Optimal lattice at fixed ρ ? Minimize

 $E: C^2_B(T^3, S^3) imes \det^{-1}(B^2/
ho^2)
ightarrow \mathbb{R}$

I.e. restrict *E* to level set of det : $SPD_3 \rightarrow (0, \infty)$.

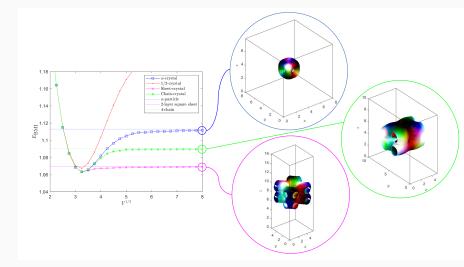
- Same argument implies (for **fixed** φ) existence of global minimizing g
- Uniqueness argument does not apply

- Baryon density $\rho = \frac{B}{\sqrt{\det g}}$
- Optimal lattice at fixed ρ ? Minimize

 $E: C^2_B(T^3, S^3) imes \det^{-1}(B^2/
ho^2)
ightarrow \mathbb{R}$

I.e. restrict *E* to level set of det : $SPD_3 \rightarrow (0, \infty)$.

- Same argument implies (for fixed φ) existence of global minimizing g
- Uniqueness argument does not apply
- Can again solve numerically by ANF



• Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!

- Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!
- Many examples in condensed matter. True also for nuclear Skyrme model with massive pions

- Energetically optimal soliton lattices do **not** necessarily have cubic (or triangular) symmetry!
- Many examples in condensed matter. True also for nuclear Skyrme model with massive pions
- Extreme case: baby Skyrme model $\varphi: M^2 \to S^2$

$$E(\varphi) = \int_M (\frac{1}{2} |d\varphi|^2 + \frac{1}{2} |\varphi^*\omega|^2 + V(\varphi).$$

Given **any** period lattice $\Lambda \subset \mathbb{R}^2$, can cook up a smooth potential $V : S^2 \to [0, \infty)$ s.t. $E(\varphi, g)$ has a global min at (φ_*, g_{Λ}) with φ_* degree 2 and holomorphic.

• So this crazy lattice **is** the period lattice of a baby Skyrmion crystal, at least for a (highly contrived) choice of V!

